e.direct **DRIVE** FOR DIRECT CURRENT MOTORS

With the e.direct drive for direct current motors, a 24VDC motor can be easily controlled and run. The electronic board is enclosed in a plastic housing designed for DIN rail mounting. When activating the "CW" and "CCW" inputs, the motor starts running

alternately clockwise and anticlockwise.

Two digital sensor inputs are provided to stop motor rotation upon activation.

The two stop signals are made available as outputs for possible connection to PLCs.

When activated, two digital sensor inputs are provided to stop motor rotation. The two stop signals are made available as outputs for possible connection to a PLC.

During acceleration and braking, the drive prevents mechanical stress on the motor and excessive energy regeneration.

Braking takes place dynamically, stopping the rotation immediately to avoid unwanted extra travel.

The rotation speed can be varied locally via the multi-turn trimmer installed on the board, or remotely, even continuously, via the analog input.

The board is equipped with 2 Hall sensor encoder inputs, NPN type and 5VDC power supply, which are fed back on two 24VDC encoder outputs, which adapt the signals coming from the Hall sensors to PLC inputs type OPEN DRAIN - PNP 24VDC.

The maximum current to be supplied to the motor can range between 1A, 2A, 3.5A and 5A via two DIP switch selectors.

When the board is not powered and the motor is stopped, the motor phases are short-circuited to increase braking torque.



| TECHNICAL DATA | | | | |
|--|-----|---|--|--|
| Code | | 37D3112000 | | |
| Motor and auxiliary power supply | VDC | 24 ±15% | | |
| Maximum power voltage | VDC | 30 | | |
| Wattage | W | 150 | | |
| Current | A | 1, 2, 3.5, 5 (Dip-switch selectable) | | |
| Temperature range | °C | -20 to 40 | | |
| Relative humidity (without condensation) | % | 5 to 85 | | |
| Dimensions | mm | 110 x 121 x 36 | | |
| Weight | g | 160 | | |
| Degree of protection | | IP20 | | |
| Digital inputs | | - no. 2, type PNP 24VDC motor rotation control (CW/CCW); | | |
| | | - no. 2, type OPEN DRAIN - PNP 24VDC limit switch (LS); | | |
| | | - no. 2, type NPN 5VDC for encoder (Hall sensors). | | |
| Digital outputs | | - no. 2, type 24VDC OPEN DRAIN - PNP suitable for PNP 24VDC PLC for limit switch (LS); | | |
| Digital oblipois | | - no. 2, 24VDC: adapting signals from Hall sensors to PLC inputs type OPEN DRAIN - PNP 24VDC. | | |
| | | | | |
| | | | | |
| Analogue inputs | | - no. 1, 0-10VDC speed adjustment from PLC or potentiometer (31400 Ω input impedance); | | |
| | | - Internal trimmer for manual speed adjustment (0-100%). | | |
| Destablish | | | | |
| Protections | | - Motor output overcurrent protection; | | |
| | | - Phase-to-phase short-circuit protection on motor; | | |
| | | - Microprocessor over-temperature protection (150°C). | | |
| Signals | | - Overvoltage (Vsupply>30VDC) - Under-voltage (Vsupply<18VDC); | | |
| Ŭ | | - With fault diagnostic output (OPEN DRAIN - PNP); | | |
| | | - Active output corresponds to one of the FAULT statuses. | | |
| | | | | |

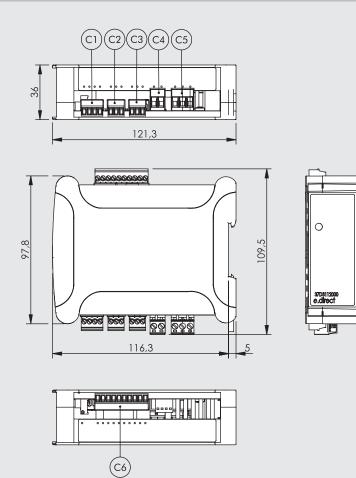
N.B.: A delayed, external fuse of a value appropriate to the set current must be provided in the system.

An appropriate external mains filter must be placed on the power supply to avoid disturbances generated by the drive.

ACTUATORS



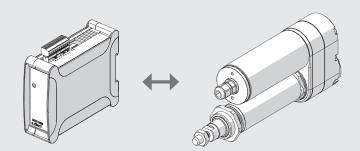
DIMENSIONS



Below is a list of Phoenix Contact codes for the board connectors.

| Connector | Description | Code Phoenix Contact | Code Phoenix Contact BASIC LINE |
|-----------|---|-------------------------|---------------------------------------|
| C1 | 4-pin plug with screw connection, MC 1.5/4 - ST - 3.5 | 1840382 | 5441223 |
| C2, C3 | 3-pin plug with screw connection, MC 1.5/3 - ST - 3.5 | 1840379 | 5441210 |
| C4 | 2-pin plug with screw connection, MC 2.5/2 - ST - 5 | 1754449 | 5441171 |
| C5 | 3-pin plug with screw connection, MC 2.5/3 - ST - 5 | 1754465 | 5448242 |
| C6 | 10-pin plug with screw connection, MC 1.5/10 - ST - 3.5 | 1840447 | 5447560 |

EXAMPLE OF CONNCETION



A5