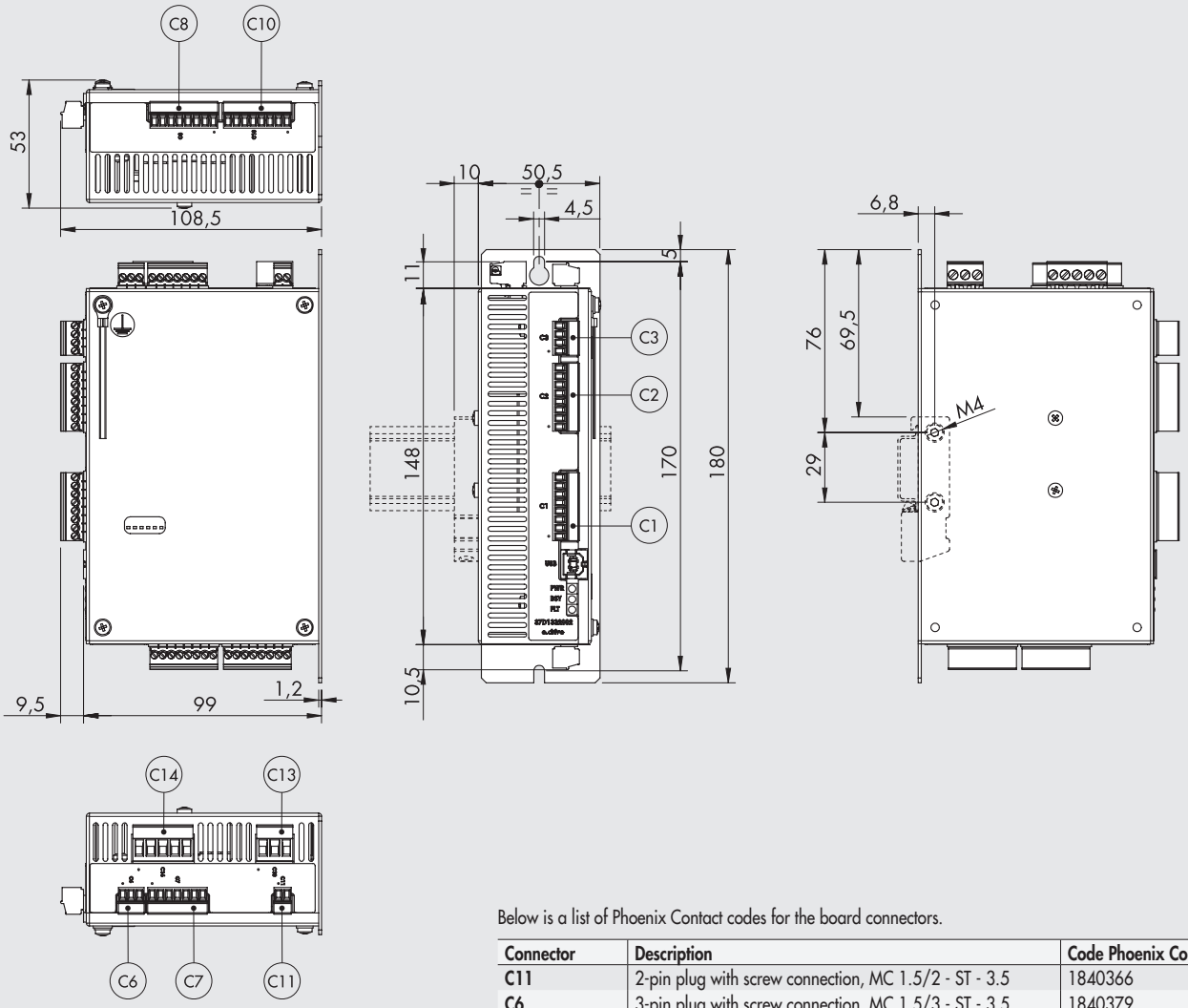
PROGRAMMABLE STEPPING MOTOR DRIVE - *e*.drive

METAL WORK PNEUMATIC

It can be used to control, easily and intuitively, electric cylinders that use a STEPPING motor with a rated current of up to 6A, two phases, with four, six or eight output wires. It connects up to a PC via a USB port and the user is provided with motion control configuration, programming and debugging environment, which allows you to create complex work cycles as it can handle both digital and analogue inputs and outputs, thanks to a user-friendly language (MW DRIVE) and a series of simple instructions and functions.
It consists of two electronic boards housed in a metal box that has been designed to be fixed onto a wall or to a DIN rail, using an accessory, and is equipped with removable screw connectors for wiring.
The electronic boards can control both the logic "motion control" stage and the power supply stage.
This independent system is ideal for use in stand-alone applications not requiring the use of any PLC.
The power stage consists of a ministep bipolar chopper drive. It is characterised by a supply voltage of up to 55VDC for the power supply side and 24VDC for the logic side, compact dimensions and great flexibility of use.

TECHNICAL DATA		
Code		**37D1332002**
Motion control logic power supply	VDC	24
Drive power supply	VDC	24 to 55
Motor phase peak current	A	1 to 6
Temperature range	°C	-20 to 40
Relative humidity (without condensation)	%	5 to 85
Bipolar motor inductance (1.8° angle)	mH	1 to 12
Dimensions	mm	148 x 99 x 50.5
Weight	g	790
Degree of protection		IP20
Communication interface		Serial USB port for connection to PC
Configuration/programming/debug and diagnosis software		MW DRIVE in Windows® environment
Dedicated signals		Encoder input (A + B + Z), 5V line driver or 24V Push-Pull/Open collector
Digital inputs		14
Digital outputs		7
Analogue inputs		2, from 0 to 10V, freely programmable
Analogue outputs		1, from 0 to 10V
Controls available		- Can be used with motors with a 1.8° base angle, 200 pulses/rev.; - Step Mode settable in various ways: Full Step, Half Step, 1/4, 1/8, 1/16 of step; - Integrated linear position transducer by connecting directly to the analogue output; - Automatic 60% reduction of the current supplied with motor stopped; - Possible dynamic regulation of the current supplied via cycle software instructions, for energy-saving purposes; - Home position search on limit switch, mechanical stop, encoder limit switch and zero mark, encoder mechanical stop and zero mark; - Positioning in relative or absolute mode; - Closed-loop motion control and step-loss control in the case of STEPPING motors with an encoder; - Integrated, automatic brake control via dedicated digital output in the case of motors with a brake; - Complementary and logical instructions for complex work cycles, such as: timings; variables control; test; analogue and digital I/O control

DIMENSIONS

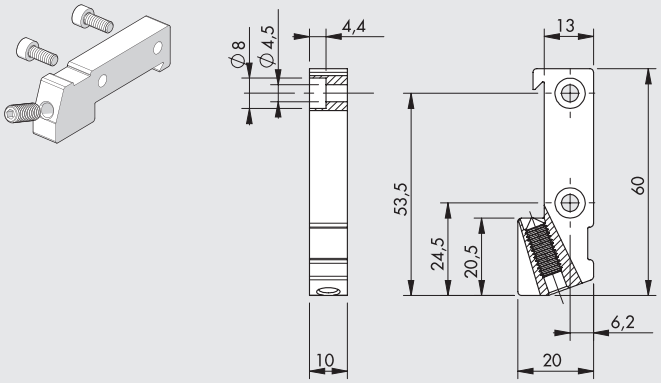


Below is a list of Phoenix Contact codes for the board connectors.

Connector	Description	Code Phoenix Contact
C11	2-pin plug with screw connection, MC 1.5/2 - ST - 3.5	1840366
C6	3-pin plug with screw connection, MC 1.5/3 - ST - 3.5	1840379
C3	4-pin plug with screw connection, MC 1.5/4 - ST - 3.5	1840382
C7	7-pin plug with screw connection, MC 1.5/7 - ST - 3.5	1840418
C1, C2, C8, C10	8-pin plug with screw connection, MC 1.5/8 - ST - 3.5	1840421
C13	3-pin plug with screw connection, MSTB 2.5/3 - ST - 5	1754465
C14	5-pin plug with screw connection, MSTB 2.5/5 - ST - 5	1754504

ACCESSORIES

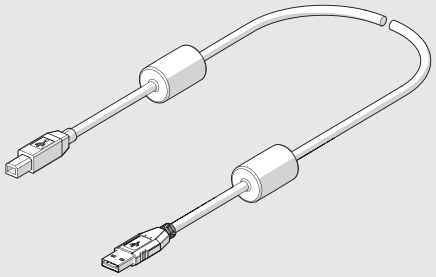
BRACKET MOUNTAING ON OMEGA BAR (DIN EN 50022)



Code	Description	Weight [g]
095000M000	Bracket mountaing ***e***.motion / ***e***.drive on Omega bar (DIN EN 50022)	30

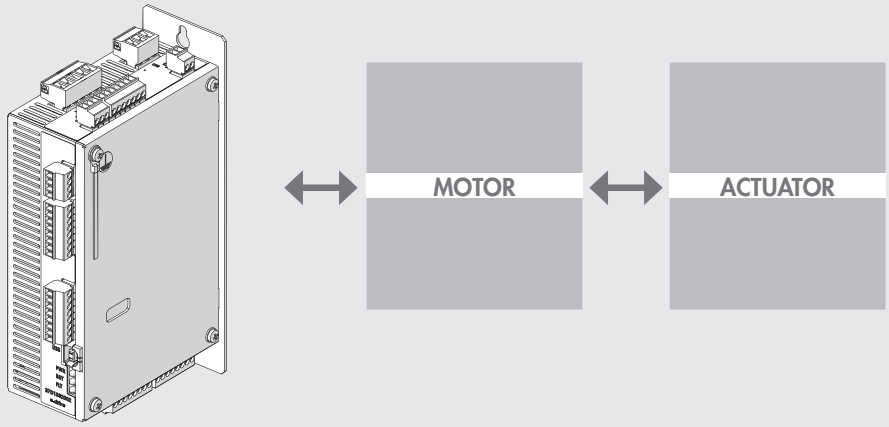
Note: Individually packed with 2 screws M4x10, 1 M6x16 grub screw

CABLE USB



Code	Description	Weight [g]
37C0030000	Cable for USB 2.0 male A-B connector with ferrite core, for connecting the **e**.motion / **e**.drive board to a PC, 3 m	150

CONNECTION SCHEME



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